

Linear Transformations Quiz Answer Key PDF

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What can be determined from the standard matrix of a linear transformation? (Select all that apply)

- A. The effect on the basis vectors \checkmark
- B. The kernel of the transformation \checkmark
- C. The range of the transformation \checkmark
- D. The inverse of the transformation

Which of the following transformations are linear? (Select all that apply)

- A. Scaling ✓
- B. Translation
- C. Rotation ✓
- D. Shearing ✓

Describe how a linear transformation can be used to rotate a vector in \(\mathbb{R}^2 \).

To rotate a vector \(\mathbf{v} = \begin{pmatrix} x \\ y \end{pmatrix} \) in \(\mathbf{R}^2 \) by an angle \(\theta \), we use the rotation matrix \(R(\theta) = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \). The rotated vector is given by \(\mathbf{v}' = R(\theta) \mathbf{v} \). \mathbf{v} \).

What is the relationship between the kernel and the injectivity of a linear transformation?

A linear transformation is injectively if and only if its kernel is trivial (only contains the zero vector).

What is the result of applying the zero transformation to any vector?

- A. The vector itself
- B. A unit vector
- C. The zero vector ✓

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D. A diagonal vector

What is a linear transformation?

- A. A function that only scales vectors
- B. A function that preserves vector addition and scalar multiplication \checkmark
- C. A function that only rotates vectors
- D. A function that maps vectors to matrices

What does the rank of a linear transformation represent?

- A. The number of vectors in the kernel
- B. The dimension of the range \checkmark
- C. The number of vectors in the domain
- D. The dimension of the kernel

Which of the following is a property of linear transformations?

- A. Non-linearity
- B. Additivity ✓
- C. Curvature
- D. Non-homogeneity

In image processing, which operation is commonly represented by a linear transformation?

- A. Blurring
- B. Scaling ✓
- C. Cropping
- D. Filtering

Discuss the process of finding the eigenvectors and eigenvalues of a matrix and their relevance to linear transformations.

To find the eigenvalues of a matrix A, we solve the characteristic equation det(A - λ I) = 0, where λ represents the eigenvalues and I is the identity matrix. Once the eigenvalues are determined, we find the corresponding eigenvectors by solving the equation (A - λ I)v = 0 for each eigenvalue λ , where v

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represents the eigenvectors. Eigenvalues and eigenvectors are significant in linear transformations as they indicate the directions in which the transformation acts by simply scaling the vectors.

What is the dimension of the kernel of a linear transformation if it is injectIVE?

- A. 0 ✓
- B. 1
- C. Equal to the dimension of the domain
- D. Equal to the dimension of the codomain

Provide an example of a real-world application of linear transformations and explain its importance.

An example of a real-world application of linear transformations is in computer graphics, where they are used to perform operations such as scaling, rotating, and translating images and 3D models.

Which of the following are properties of linear transformations? (Select all that apply)

- A. Additivity ✓
- B. Homogeneity ✓
- C. Non-linearity
- D. Communtativity

How does a change of basis affect the matrix representation of a linear transformation?

The matrix representation of a linear transformation changes according to the formula: $A' = P^{(-1)}AP$, where A is the original matrix, A' is the new matrix in the new basis, and P is the change of basis matrix.

Which of the following transformations is not linear?

- A. Rotation
- B. Reflection
- C. Translation ✓
- D. Scaling

Which of the following are true about the kernel of a linear transformation? (Select all that apply)

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- A. It contains the zero vector \checkmark
- B. It is a subspace of the domain \checkmark
- C. It is always non-empty ✓
- D. It is equal to the range

Which of the following matrices can represent a linear transformation in $(\mathbb{R}^2)?$ (Select all that apply)

- A. \(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \) ✓
- B. \(\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \) ✓
- C. \(\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \)
- D. \(\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \) ✓

In which scenarios is diagonalization applicable? (Select all that apply)

- A. When the matrix is invertible
- B. When the matrix has distinct eigenvalues \checkmark
- C. When the matrix is symmetric \checkmark
- D. When the matrix is singular

Which matrix represents the identity transformation in \(\mathbb{R}^2 \)?

- A. \(\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \)
- B. \(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \) ✓
- C. \(\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \)
- D. \(\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \)

Explain the significance of the rank-nullity theorem in the context of linear transformations.

The rank-nullity theorem states that for a linear transformation from a vector space V to a vector space W, the dimension of V (the number of vectors in a basis for V) is equal to the rank of the transformation (the dimension of the image) plus the nullity of the transformation (the dimension of the kernel). This theorem is significant because it helps us understand how many dimensions are 'lost' in the transformation and how many are preserved.